

Malcolm A. MacIver
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Northwestern University Interdepartmental Neuroscience Program
Northwestern University Institute on Complex Systems
Segal Design Institute

EDUCATION

2001 PhD Neuroscience, University of Illinois and the Beckman Institute of Advanced Science and Technology, Urbana IL
1996 Course work only of dual Ph.D. in cognitive science and philosophy, Indiana University, Bloomington IN
1992 MA Philosophy, University of Toronto
1991 BSc Double major in computer science and philosophy, University of Toronto, graduated with High Distinction
1986 AEE Electrical Engineering Technician, Confederation College, Thunder Bay, Ontario Canada

PROFESSIONAL EXPERIENCE

2016-present Professor (Joint between Dept. of Mechanical Engineering & Dept. of Biomedical Engineering), and Dept. of Neurobiology by Courtesy, Northwestern University
2010-2016 Associate Professor (Joint between Dept. of Mechanical Engineering & Dept. of Biomedical Engineering), and Dept. of Neurobiology by Courtesy, Northwestern University
2003-2010 Assistant Professor (Joint between Dept. of Mechanical Engineering & Dept. of Biomedical Engineering), and Dept. of Neurobiology by Courtesy, Northwestern University
2001-2003 Postdoctoral Fellow, Division of Engineering and Applied Science, Computation and Neural Systems Program, and Center for Neuromorphic Systems Engineering, California Institute of Technology, Pasadena CA

HONORS AND AWARDS

- 2018 US Embassy, New Zealand invited visit to New Zealand, with lectures and round-table discussions in Dunedin, Wellington, and Auckland New Zealand.
- 2017 Keynote speaker, German Zoological Society 110th Annual Meeting. Bielfeld, Germany.
- 2014 Symposium speaker for American Association for the Advancement of Science session on biologically inspired robotics, Chicago IL
- 2014 Plenary Speaker at the International Congress of Neuroethology, August 2014, Sapporo Japan.
- 2013 TEDx Caltech “The Brain” closing speaker, “Can We Expand Our Consciousness with Neuroprosthetics?” Jan 18, 2013.
- 2009 Received Presidential Early Career Award for Science and Engineering from Barack Obama at the White House
- 2009 Recipient, National Science Foundation CAREER Award
- 2006 Invited Distinguished Evening Lecturer, MBL at Woods Hole Summer Course in Neural Systems and Behavior
- 2003 Invited Panelist, *Issues at the Intersection of Art and Science*, Center for Neuromorphic Systems Engineering at Caltech and the Art Center's Alyce de Roulet Williamson Gallery, Pasadena CA
- 2003 Recipient, Center for Neuromorphic Systems Engineering NEURO Art Installation Development Award for **Body Electric**
- 1999 Selected to attend the Telluride Neuromorphic Engineering Workshop
- 1997 Beckman Institute for Advanced Science and Technology Research Assistantship
- 1995 Scholarship to Attend the Princeton Lectures on Biophysics
- 1994 McDonnell Summer Institute in Cognitive Neuroscience Scholarship
- 1993 Cognitive Science Summer Research Fellowship, Indiana University
- 1992 Summer internship, Artificial Intelligence, Canadian National Research Council
Developed automatic natural language explanations of military jet engine faults
- 2001 Best Exhibit, Beckman Institute for Advanced Science Open House
- 1991 Graduated with High Distinction (University-wide graduating class GPA Award)

CORE AREAS OF INTEREST

The mechanical basis of information harvesting in animals. The analysis of the metabolic cost of information for animals has proven to be a useful approach to understanding a variety of patterns within neuronal systems. These analyses have uncovered a host of ways that nervous systems reduce their energetic footprint. A missing piece of the puzzle, however, is that animals frequently move in order to obtain better sensory information. Thus an analysis of the energetics of neurons needs to be complemented by an analysis of the energetics of movement related to improving signal. To that end, we have developed a novel way to characterize the “motor

range”—analogous to sensory range—of an animal based on concepts from nonlinear control engineering. Using this concept, we have shown that a unique feature of active sensing animals is that they sense in a “just-in-time” fashion, such that if they sensed at a shorter range, they would collide with their target. We have documented a host of motor system adaptations that make such reactive mode control possible while still maintaining stability. Relevant work: J25, C09, J14, J08. [Video explaining ergodic algorithm for active sensing \(11:34, 2019\)](#).

Mechanics of undulatory propulsion. Over a thousand aquatic species use undulatory fins for movement. We have characterized key principles of the generation of propulsion from these structures, along with flow structure characterization, and stability and maneuverability implications. We have discovered convergent evolution of a mechanically optimal form of fin undulation across almost two dozen species in three phyla; that inwardly counter-propagating traveling waves are often used by these swimmers to simultaneously enhance maneuverability and stability as well as provide a direction of thrust that is at right angles to the axis of the propulsor; and that flow structures emanating from these fins have unique features compared to tail-flapping type swimmers. Our analysis across experimental fluids, computational fluids, and reduced order models is one of the first times an animal propulsor has been characterized to an extent sufficient for high performance, well-controlled robotic implementation. Relevant work: J24, J22, J21, J20, J17, J16, J15, J13, J12, J11.

Robots and algorithms targeting bio-inspired sensing and movement. A key means for advancing our work on sensorimotor integration has been a fleet of specialized robots for robotic experimentation and synergy with biological efforts. One lineage of these robots deploys an engineered version of active electrosense, the first time that active electrosense has been translated into a working machine, and an inspiration for several groups that now pursue engineered electrosense. Another lineage of robots take their cue from the unique propulsion system of electric fish, using undulation of an elongated fin on a rigid body for propulsion during swimming. Some of the key findings in the electrosense robotics work include development of the first algorithm to determine the shape, size, and distance of spheroids using active electrosense; development of “stereo” electrosense that detects complex impedance. The biomimetic propulsion robotics efforts have resulted in understanding an animal mode of movement to a sufficient level of detail to enable high performance, well-controlled robotic motion. Relevant work: J26, J27, J25, C09, J23, J19, J16, J09, C08, C10, C07, C06, C05, C04, C03, C02, J04. [Video on applications of electric fish robots \(00:25, 2014\)](#). [Video explaining ergodic algorithm for active sensing \(11:34, 2019\)](#).

Evolution of movement and higher cognitive capacities. Air is vastly more transparent than water, an observation that led us to examine how vision changed when fish invaded land around 350 million years ago. We have discovered that eyes nearly tripled in size just prior to invasion of land, and we are able to show through computational visual ecology simulations that this tripling was for vision through air. Thus prior to emergence of limbs, our vertebrate ancestors were hunting a bounty of terrestrial invertebrates from the water while seeing through air—in short, similar to how crocodiles hunt. We show that the visual sensory volume grows by more than a factor of a million times between life in water and life on land, with dramatic implications for the utility of advanced planning and neural control mechanisms, which are otherwise not necessary when reactive control is all that can work due to short sensing ranges. Newer work

shows that the utility of planning increases greatly with sensory range and with the complexity of the habitat. Planning appears to require significant computation in animal brains; thus the fact that 10,000 times more energy is needed to extract a given amount of oxygen within water compared to air may be another factor for why it seems largely restricted to warm blooded land animals.

Relevant work: J34, J32, C14, J29, [short animation on why fish came up on to land](#), J28, I02, B33, B34, B35, J08, J14, J24, I04. [TedXCaltech video on connection between motor & sensory volumes and consciousness](#).

Quantification of prey capture behavior and volumetric light field imaging of associated circuits. Through a combination of a custom infrared videography system for fish behavior, a partially automatic 3D tracking system, and a series of computational models, we calculated the full array of sensory signal input that occurs when weakly electric fish pursue their live prey. This was done for active electrosense, passive electrosense, and lateral line mechanosense. This is one of the first times the full array of sensory signals relating to a complex natural behavior has been estimated for any animal. More recently we have begun to work on the larval zebrafish model system and quantification of prey capture in this system, associated visual signals, and reticulospinal circuit function as measured through volumetric light-field microscopy with calcium indicators. Our objective is to use the full suite of tools we have developed within our electric fish research (quantitative behavioral analysis, modeling, simulation, and robo-physical models) to a system where neural circuits are more easily probed with modern imaging and genetic tools. The overall objective of this portion of our work is to obtain a mechanistic understanding of how sensing, mechanics, and neural circuitry is interwoven for high agility in complex environments, and how this can be emulated in robots. Relevant work: J33, J30, J18, J08, J07, J05, J03, J02, J01, C01.

PEER REVIEWED JOURNAL ARTICLES

*ASTERISK INDICATES CO-CORRESPONDING AUTHOR

PDFs: [HTTPS://ROBOTICS.NORTHWESTERN.EDU/RESEARCH/PUBLICATIONS](https://robotics.northwestern.edu/research/publications)

J34 Hunt, L.T, Daw, N.D, Kaanders, P., MacIver, M.A., Mugan, U., Procyk, E., Redish, A.D., Russo, E., Scholl, J., Stachenfeld, K., Wilson, C.R.E., and Kolling, N., Formalising planning and information search in naturalistic decision-making. Under review, *Nature Neuroscience*.

J33 Bhattacharyya, Kiran D. and McLean, David L. and MacIver, M. A. Intersection of motor volumes predicts the outcome of ambush predation of larval zebrafish. Under revision, *Journal of Experimental Biology*.

J32 Mugan, U. and MacIver, M.A. (2020) Spatial planning with long visual range benefits escape from visual predators in complex naturalistic environments. [Nature Communications](#). [Video explainer](#).

J31 Chen, C. Murphey, T.D, and MacIver, M.A. (2020) Tuning movement for sensing in an uncertain world, [eLife](#). Videos: [Behaviors](#), [Application of theory to a robot](#).

J30 Bhattacharyya, Kiran D. and McLean, David L. and MacIver, M. A. (2017) Visual threat assessment and reticulospinal encoding of calibrated responses in larval zebrafish. *Current Biology* 27, 2751–2762.

J29 MacIver, M.A., Schmitz, L., Mugan, U, Murphey, T.D, and Curtis D. Mobley (2017). Massive increase in visual range preceded the origin of terrestrial vertebrates. *Proceedings of the National Academy of Sciences*, 114(12):E2375-E2384. doi: 10.1073/pnas.1615563114 [Link to Open Access PDF](#).

Video explainer/outreach: <https://youtu.be/I19usgWHJLc>.

Commentary: Evolution, an Irresistibly Clear View of Land, by Dan-E. Nilsson. *Current Biology*, 2017, <http://dx.doi.org/10.1016/j.cub.2017.05.082>. Response by MacIver & Schmitz: [http://www.cell.com/current-biology/comments/S0960-9822\(17\)30648-6](http://www.cell.com/current-biology/comments/S0960-9822(17)30648-6).

J28 Krakauer, J.W., Ghazanfar, A.A., Gomez-Marin A., MacIver, M.A., and David Poeppel (2017). Neuroscience Needs Behavior: Correcting a Reductionist Bias. *Neuron*, 93(3): 480-490.

J27. Fang, S., Peshkin, M. and MacIver, M. A. (2016) Human-in-the-loop active electrosense. *Bioinspiration & Biomimetics*, vol 12, issue 1, pp. 014001, 12/2016, doi:10.1088/1748-3190/12/1/014001.

J26. Bai, Y., Neveln I.D., Peshkin M., and MacIver, M. A. (2016) Enhanced detection performance in electrosense through capacitive sensing. *Bioinspiration & Biomimetics*. doi:10.1088/1748-3190/11/5/055001.

J25. Miller, L. M., Y. Silverman, M. A. MacIver, and T. D. Murphey (2016). Ergodic Exploration of Distributed Information. *IEEE Transactions on Robotics*, 32(1), 36-52. [Link to video](#) explaining the algorithm (Script and narration: MacIver).

J24. Bale, R., A. P. S. Bhalla, I. D. Neveln, M. A. MacIver*, and N. A. Patankar (2015). Convergent evolution of mechanically optimal locomotion in aquatic invertebrates and vertebrates. *PLOS Biology* 2015, DOI: 10.1371/journal.pbio.1002123.

J23. Bai, Y., J. B. Snyder, M. A. Peshkin, and M. A. MacIver, Localizing and identifying underwater objects with active electrosense (2015). *The International Journal of Robotics Research*. DOI: 10.1177/0278364915569813.

J22. Bale, R. A., Shirgaonkar, A. A., Neveln, I. D., Bhalla, A. P. S., MacIver, M. A., Patankar, N.A. Separability of drag and thrust in undulatory animals and machines (2014). *Scientific Reports* (4), doi:10.1038/srep07329.

J21. Neveln, I. D., Bale, R., Bhalla, A. P. S., Curet, O. M., Patankar, N. A., MacIver, M. A. (2014) Undulating fins produce off-axis thrust and flow structures. *Journal of Experimental Biology*, 217, 201-213.

J20. Sefati, S., I. Neveln, E. Roth, T. Mitchell, J. B. Snyder, M. A. MacIver, E. S. Fortune, and Cowan, N. J. (2013). Mutually opposing forces during locomotion can eliminate the tradeoff between maneuverability and stability. *Proceedings of the National Academy of Sciences*, 110 (47) 18798-18803.

- J19. Neveln, I. D., Bai, Y., Snyder, J. B., Solberg, James R., Curet, O. M., Lynch, Kevin M., & MacIver, M. A. (2013). Biomimetic and bio-inspired robotics in electric fish research. *Journal of Experimental Biology*, 216, 2501-2514.
- J18. Patterson, B.W., Abraham, A.O., MacIver, M.A., & McLean, D. L. (2013). Visually guided gradation of prey capture movements in larval zebrafish. *Journal of Experimental Biology*, 216, 3071-3083.
- J17. Ruiz-Torres, R., Curet, O. M., Lauder, G. V., & MacIver, M.A. (2012). Kinematics of the ribbon fin in hovering and swimming of the electric ghost knifefish. *Journal of Experimental Biology*, 216, 823-834.
- J16. Curet, O.M., Patankar, N. A., Lauder, G.V., MacIver, M. A. (2011) Mechanical properties of a bio-inspired robotic knifefish with an undulatory propulsor. *Bioinspiration & Biomimetics*, Jun;6(2):026004. Epub April 7, 2011, doi:10.1088/1748-3182/6/2/026004.
- J15. Curet, O.M., Patankar, N. A., Lauder, G.V., MacIver, M. A. (2011) Aquatic maneuvering with counter-propagating waves: a novel locomotive strategy. *Journal of the Royal Society Interface*, July 6; 8(60):1041-50 Epub Dec 22, 2010, doi: 10.1098/rsif.2010.0493. **Cover.**
- J14. MacIver, M.A., Patankar, N. A., Shirgaonkar, A. A. (2010) Energy-information trade-offs between movement and sensing. *PLoS Computational Biology* 6(5): e1000769. doi:10.1371/journal.pcbi.1000769.
- J13. Curet, O.M., AlAli, I. K., MacIver, M.A., Patankar, N. A. (2010) A versatile implicit iterative approach for fully resolved simulation of self-propulsion. *Computer Methods in Applied Mechanics and Engineering*, doi:10.1016/j.cma.2010.03.026.
- J12. Shirgaonkar, A. S., MacIver, M. A., Patankar, N. A. (2009) A new mathematical formulation and fast algorithm for fully resolved simulation of self-propulsion. *Journal of Computational Physics*, 228, 2366-2390.
- J11. Postlethwaite, C. M., Psemeneki, T. M., Selimkhanov*, J., Silber, M., MacIver, M. A. (2009) Optimal movement in the prey strikes of weakly electric fish: A case study of the interplay of body plan and movement capability. *Journal of the Royal Society Interface*. Published online Oct 8, 2008; doi:10.1098/rsif.2008.0286; published in journal 2009. *Undergraduate researcher.
- J10. Shirgaonkar, A. A., Curet, O.M., Patankar, N. A., MacIver, M. A. (2008) The hydrodynamics of ribbon-fin propulsion under impulsive motion. *Journal of Experimental Biology* 211: 3490-3503.
- J09. Solberg, J. R., Lynch, K. M., & MacIver, M. A. (2008). Active electrolocation for underwater target localization. *International Journal of Robotics Research*, 27(5), 529-548.
- J08. Snyder, J.B., Nelson, M.E., Burdick, J. W., MacIver, M.A. (2007) Omnidirectional sensory and movement volumes in electric fish. *PLoS Biology* 5(11): e301.
- J07. Nelson, M.E. and MacIver, M.A. (2006) Sensory acquisition in active sensing systems. *Journal of Comparative Physiology A* 192: 573-586.

- J06. MacIver, M.A., Fontaine, E., Burdick, J. W. (2004) Designing future underwater vehicles: principles and mechanisms of the weakly electric fish. *IEEE Journal of Oceanic Engineering* 29(3):651-659.
- J05. Nelson, M.E., MacIver, M.A., Coombs, S. (2002) Modeling electrosensory and mechanosensory images during the predatory behavior of weakly electric fish. *Brain, Behavior, and Evolution* 59(4): 199-210.
- J04. MacIver, M.A., Nelson, M.E. (2001) Towards a biorobotic electrosensory system. *Autonomous Robots* 11, 263–266.
- J03. MacIver, M.A., Sharabash, N. M., Nelson, M.E. (2001) Prey-capture behavior in gymnotid electric fish: motion analysis and effects of water conductivity. *Journal of Experimental Biology*, 204(3): 543-557.
- J02. MacIver, M.A., Nelson, M.E. (2000) Body modeling and model-based tracking for neuroethology. *Journal of Neuroscience Methods*, 95(2):133-143.
- J01. Nelson, M.E., MacIver, M.A. (1999) Prey capture in the weakly electric fish *Apteronotus albifrons*: Sensory acquisition strategies and electrosensory consequences. *Journal of Experimental Biology*, 202(10):1195-1203. **Cover.**

INVITED BOOK CHAPTERS, REVIEWS, ARTICLES, ETC

PDFs: [HTTPS://ROBOTICS.NORTHWESTERN.EDU/RESEARCH/PUBLICATIONS](https://robotics.northwestern.edu/research/publications)

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- I04. MacIver, M. A. (2013) Engineering Health and Sustainability through Consciousness-Enhancing Technologies, *McCormick Magazine*, Spring 2013, Northwestern University, pp. 18-19.
- I03. MacIver, M. A. Fitting Science and Screen [Book Review]. *Science*, 6 May 2011: Vol. 332 no. 6030 p. 665. DOI: 10.1126/science.1205130.
- I02. MacIver, M.A. Neuroethology: From Morphological Computation to Planning (2009). *The Cambridge Handbook of Situated Cognition*, Robbins P. & Aydede, M. (eds). Cambridge University Press: Chapter 26, 480-504.
- I01. MacIver, M.A. (2001) How building physical models can reduce and guide the abstraction of nature. *Brain and Behavioral Sciences* 24(6):1066-1067.

VIDEO ANIMATION

2017. Our Short-Sighted Inner Fish. Written and Produced by Kristin Pichaske in collaboration with Malcolm A. MacIver. Animation by Kaleida Studios and Cartuna. Animators: Julie Gratz, Kevin Ryan, and Kinga Nagorka. Music and Sound: Noah Pardo. [Link to video](#). 70,000+ views as of Dec 2019.

ART SHOWS

2011 **scale**, Malcolm A. MacIver, Marlena Novak, and Jay Allan Yim. **translife**, International Triennial of New Media Art. **National Art Museum of China**, July 27—August 17, 2011, Beijing, China. **Documentation:** [Exhibit Statement and Video at this web location](#). Estimated participation: 10,000.

2010 **scale**, Malcolm A. MacIver, Marlena Novak, and Jay Allan Yim. World premiere at the **STRP Festival of Art and Technology in Eindhoven**, The Netherlands, Nov 18-28 2010. The [STRP](#) Festival is one of the largest e-culture events in Europe which melds music, art & technology together. 30,000 people visited the festival during the premiere.

2003 **Body Electric**, Malcolm A. MacIver and Simon Penny. **Williamson Art Gallery** in the Art Center College of Design in Pasadena CA, April 15-June 29 2003. Part of the NEURO exhibition developed by the Caltech Center for Neuromorphic Systems Engineering and the Williamson Art Gallery. **Documentation:** [Exhibit Statement and Video at this web location](#).

SELECT MOVIE AND TV SERIES SCIENCE ADVISING

2015 Advisor, *Terminator Genisys*

2015 Advisor, *The Avengers: Age of Ultron*

2013 Advisor, *Superman, Man of Steel*

2010 *Tron Legacy*

2009-2010 Robotics & science script consultant for SyFy Channel's prequel to Battlestar Galactica, *Caprica*, Seasons 1 & 2.

PEER REVIEWED CONFERENCE PROCEEDINGS

PDFs: [HTTPS://ROBOTICS.NORTHWESTERN.EDU/RESEARCH/PUBLICATIONS](https://robotics.northwestern.edu/research/publications)

C14. Ugurcan, M., M. A. MacIver. How sensory ecology affects the utility of planning, 2018. Conference on Cognitive Computational Neuroscience, Philadelphia PA. Sept 2018.

C13. Mamakoukas, G., M. A. MacIver, and T. D. Murphey, Superlinear Convergence Using Controls Based on Second-Order Needle Variations, 2018. IEEE Conference on Decision and Control, Miami Beach FL.

C12. Ugurcan, M., M. A. MacIver, and M. Peshkin, Information-theoretic approach to sensor selection, 2017. The 8th International Symposium on Adaptive Motion of Animals and Machines, Sapporo Japan.

C11. Mamakoukas, G., M. A. MacIver, and T. D. Murphey, Feedback Synthesis for

Controllable Underactuated Systems using Sequential Second Order Actions, Robotics: Science and Systems, 2017.

C10. Mamakoukas, G., M. A. MacIver, and Todd. D. Murphey. Sequential Action Control for Models of Underactuated Underwater Vehicles in a Planar Ideal Fluid. American Control Conference, Boston MA, 2016.

C09. Neveln, I. D., L. M. Miller, M. A. MacIver, and T. D. Murphey, Improving Object Tracking through Distributed Exploration of an Information Map, IEEE Int. Conf. on Intelligent Robots and Systems (IROS), 2014. Pages: 3441 - 3447, doi: 10.1109/IROS.2014.6943042.

C08. Silverman, Y., L. M. Miller, M. A. MacIver, and Murphey, T.D. (2013) Optimal Planning for Information Acquisition. Intelligent Robots and Systems (IROS), 2013 IEEE/RSJ International Conference, p5974-5980, Tokyo Japan. doi: 10.1109/IROS.2013.6697223

C07. Shahin Sefati, Izaak Neveln, Malcolm A. MacIver, Eric Fortune, Noah J. Cowan (2012). Counter-Propagating Waves Enhance Maneuverability and Stability: A Bio-Inspired Strategy for Robotic Ribbon-Fin Propulsion. Biomedical Robotics and Biomechanics (BioRob), 2012 4th IEEE RAS & EMBS International Conference on, pp. 1620-1625. DOI: 10.1109/BioRob.2012.6290909.

C06. Yonatan Silverman, James Snyder, Yang Bai, and Malcolm A. MacIver (2012) Location and Orientation Estimation with an Electrosense Robot. Intelligent Robots and Systems (IROS), 2012 IEEE/RSJ International Conference on, pp.4218-422e, 7-12 Oct. 2012. doi: 10.1109/IROS.2012.638617.

C05. Bai, Y., Snyder, J. B., Silverman, Y., Peshkin, M. and MacIver, M.A. (2012). Sensing Capacitance of Underwater Objects in Bio-inspired Electrosense. Intelligent Robots and Systems (IROS), 2012 IEEE/RSJ International Conference on, pp.1467-1472, 7-12 Oct. 2012. doi: 10.1109/IROS.2012.638617.

C04. Snyder, J., Silverman, Y., Bai, Y. MacIver, M.A., (2012). Underwater object tracking using electrical impedance tomography. Intelligent Robots and Systems (IROS), 2012 IEEE/RSJ International Conference on, vol., no., pp.520-525, 7-12 Oct. 2012 doi: 10.1109/IROS.2012.6386251.

C03. Epstein, M., Colgate, J.E, MacIver, M.A. (2006) Generating Thrust with a Biologically-Inspired Robotic Ribbon Fin Source. 2006 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) Beijing, China. pp: 2412 - 2417, DOI: 10.1109/IROS.2006.281681.

C02. Epstein, M., Colgate, J.E, MacIver, M.A. (2005) A Biologically Inspired Robotic Ribbon Fin. Proceedings of the 2005 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), workshop on Morphology, Control, and Passive Dynamics.

C01. MacIver, M.A., Lin, J.L., Nelson, M.E. (1997) Estimation of signal characteristics during electrolocation from video analysis of prey capture behavior in weakly electric fish.

Computational Neuroscience: Trends in Research, 1997. Plenum Press. pp. 729-734.

SELECT ONLINE TALKS

- 2019 Terrestrial sensory ecology provides a selective benefit to planning. COSYNE workshop 'Beyond trial-based choice: decision-making in naturalistic and temporally extended environments' in Cascais Portugal. <https://youtu.be/Q3H-5Z3-6gM>.
- 2018 Mechanically optimal movement in fish and its coupling to information harvesting. University of Auckland, Auckland Bioengineering Institute. Auckland New Zealand. <https://www.youtube.com/watch?v=gAHcUyP3IDE>.
- 2018 How sentience changed after fish invaded land 385 million years ago. UQAM / ISC 2018 Summer School in Animal Cognition - The other minds problem: animal sentience and cognition. University of Quebec, Montreal Canada. https://youtu.be/HI7fXIP_mjo.
- 2014 Electric fish robotics. AAAS National Meeting, Symposium on “Intelligent Autonomous Robots: Biologically Inspired Engineering”, Chicago IL. <https://vimeo.com/87924126>.
- 2013 Can We Expand Our Consciousness With Neuroprosthetics? TEDx Caltech, January 2013. Pasadena CA. <https://youtu.be/gj2zx1kEjKM>.
- 2011 Energy, Information, and the Emergence of Choice. FQXi Conference, Copenhagen. <https://youtu.be/dRDfwsuBNb4>.

INVITED TALKS AT PROFESSIONAL SYMPOSIA

- 2021 Tuning movements for sensing in an uncertain world. August 22-24 Active Sensing: From Animals to Robots. Weizmann Institute, Tel-Aviv, Israel.
- 2019 Terrestrial sensory ecology provides a selective benefit to planning. March 5 2019 COSYNE workshop 'Beyond trial-based choice: decision-making in naturalistic and temporally extended environments' in Cascais Portugal.
- 2018 How sensory ecology affects the utility of planning. Computational Cognitive Neuroscience, September 5, Philadelphia 2018 USA.
- 2018 Evolving from reactivity to deliberation: steps in getting more time to think. Santa

- Fe Institute Workshop on the Origins & Implications of Time in Physical & Adaptive Systems. Santa Fe, New Mexico.
- 2018 How sentience changed after fish invaded land 385 million years ago. UQAM / ISC 2018 Summer School in Animal Cognition - The other minds problem: animal sentience and cognition. University of Quebec, Montreal Canada.
- 2018 Animal habitat as an evolutionary driving force for the development of planning systems. J. B. Johnston Club for Evolutionary Neuroscience, San Diego, CA.
- 2016 Mechanically optimal movement in fish and its coupling to information harvesting. Fifth annual winter workshop in the neuromechanics and dynamics of locomotion, Tulane University, New Orleans LA.
- 2015 Electric Fish Robotics. 7th International Symposium on Adaptive Motion of Animals and Machines. MIT, Cambridge MA.
- 2014 Vision versus electrosense. 26th Annual Karger Workshop in Evolutionary Neuroscience. November 2014, Washington DC.
- 2014 Electric fish robotics. AAAS National Meeting, Symposium on “Intelligent Autonomous Robots: Biologically Inspired Engineering”, Chicago IL.
- 2013 Vision versus electrosense: Mechanics and sensing in prey capture behavior of larval zebrafish compared to electric knifefish. Janelia Farms Conference, “Dynamics of Prey Capture and Escape” March 2013, Ashburn, VA.
- 2013 Can We Expand Our Consciousness With Neuroprosthetics? TEDx Caltech, January 2013. Pasadena CA.
- 2013 Vision versus electrosense: Mechanics and sensing in prey capture behavior in larval zebrafish compared to electric knifefish. Symposium keynote for “When Predators Attack,” Society of Integrative and Comparative Biology, January 2013, San Francisco, CA.
- 2012 How Knifefish Swim: Spanning the Gap Between Eel-like and Trout-Like Swimming. Weakly electric fish meeting, International Congress of Neuroethology August 2012, College Park MA.
- 2012 Sensory and Motor Spaces and the Emergence of Multiple Futures. Computational Neuroscience Annual Meeting, July 2012, Atlanta GA. (keynote).
- 2012 Sensory and Motor Spaces and the Emergence of Multiple Futures. Summer School in Cognitive Sciences, “The Evolution and Function of Consciousness,” June 30-July 9, Montreal Canada.
- 2012 “From electric fish to robot fish and back” PINC Conference, Amsterdam,
- 2011 “Energy, Information, and the Emergence of Choice” FQXi Conference, Copenhagen.
- 2011 “Energy-Information Trade-Offs between Movement and Sensing,” Gordon

- Conference on Neuroethology.
- 2011 “Energy-Information Trade-Offs between Movement and Sensing.” International workshop on bio-inspired robots, Nantes France (keynote).
- 2011 “Energy-Information Trade-Offs between Movement and Sensing.” German Society for Neuroscience, Gottingen.
- 2010 “Infomechanics and the bone-brain continuum.” Swiss Federal Institute of Technology, Life Science Symposium on Engineering Life, Lausanne, Switzerland.
- 2009 “The development of a bio-inspired magneto-electrosensory navigation module.” Office of Naval Research Symposium on Bio-inspired Systems, Washington DC
- 2009 “Biomechanical constraints on sensory acquisition in weakly electric fish” Society for Integrative and Comparative Biology, Symposium on Sensory Biomechanics, Boston, MA
2008. “Acquiring information under mechanical constraints” Fourth International Symposium on Adaptive Motion of Animals and Machines, Case Western Reserve University, Cleveland, OH
- 2007 “Sensory and movement volumes in animals: Implications for control” Symposium on top-down influences in active sensing. International Congress of Neuroethology, Vancouver BC Canada
- 2007 “Infomechanical specializations for maximizing prey capture in the knifefish” Satellite meeting on electrosensory organisms, International Congress of Neuroethology, Vancouver BC Canada
- 2007 “Robotic electrolocation: Active underwater target localization with electric fields.” Solberg, J.S., Lynch, K.M., and MacIver, M.A. International Conference for Robotics and Automation, Symposium on Bio-inspired Perception, Rome, Italy. Presenter: Solberg.
- 2006 “From morphological computation to planning: insights from neuroethology,” Tenth International Conference on the Simulation and Synthesis of Living Systems (ALife X), Workshop on Morphologies, Motion and Cognition, Bloomington, IN, USA
- 2006 “Generating Thrust with a Biologically-Inspired Robotic Ribbon Fin.” Epstein, M., Colgate, J. E., MacIver, M.A. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Beijing, China. Presenter: MacIver.
- 2005 “Explorations in Computational Morphology,” The Canadian Electric Fish Meeting, Merrickville, ON, Canada
- 2005 “A Biologically Inspired Robotic Ribbon Fin.” Epstein, M., Colgate, J. E., MacIver, M. A. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Edmonton, AB, Canada. Presenter: MacIver.

- 2004 “Matching of sensing and motor volumes in active sensory systems.” MacIver, M. A., Nelson, M. E., Burdick, J. W. Society for Neuroscience Satellite Symposium on Advances in Computational Motor Control, San Diego, CA, USA. Presenter: MacIver
- 2004 “Matching of sensing and motor volumes and optimality of movements in active sensory systems,” Center for Neuromorphic Systems Engineering 10th Anniversary Celebration.
- 2003 “Neuromechanical design and active sensory systems,” 13th International Symposium on Unmanned Untethered Submersible Technology, Durham, NH, USA
- 2003 “Getting around on a small charge: mechanics, sensing, and biorobotics with the weakly electric fish,” Second International Symposium on Aqua Bio-Mechanisms, Honolulu, HI, USA
- 2002 “Sensing, mechanics, and control: a framework for the integrated understanding of a natural behavior,” The Hebrew University and Caltech 2nd Joint Symposium on Frontiers in Computational Neuroscience, Pacific Grove, CA, USA
- 2000 “A robotic implementation of electrosensory signal acquisition in electric fish,” NASA Workshop on Biomorphic Robotics, Pasadena, CA, USA

OTHER INVITED ACADEMIC TALKS

- | | |
|---|------|
| 1. Columbia University, Zuckerman Mind Brain Behavior Institute | 2020 |
| 2. University of Auckland, Bioengineering Program | 2018 |
| 3. University of Otago, Department of Zoology | 2018 |
| 4. University of Cincinnati, Department of Psychology | 2018 |
| 5. Washington and Lee University, Physics-Engineering Seminar Series | 2015 |
| 6. University of Chicago, Chicago IL, Computational Neuroscience Seminar Series | 2013 |
| 7. University of Wisconsin, Milwaukee, Dept. of Neurobiology | 2013 |
| 8. Cornell University, Distinguished Speaker Series, BBS Seminar | 2013 |
| 9. Grand Rounds, Northwestern Department of Psychiatry | 2013 |
| 10. University of Washington, Seattle, Dept. of Computer Science & EE | 2012 |
| 11. iRobot, Durham NC | 2010 |
| 12. International Neuroethology Congress, Coupled Robot-Animal Systems | 2010 |
| 13. Northwestern University Institute of Neuroscience Retreat, St. Charles IL | 2009 |
| 14. Slivka Residence Hall Fireside Science Talk, Evanston IL | 2009 |
| 15. Dept. of Engineering Sci., U. of Illinois Urbana-Champaign | 2009 |
| 16. Division of Eng., & Dept. of Ecology and Evolutionary Biology, Brown University | 2009 |
| 17. Dept. of Biomedical Engineering, University of California Irvine | 2008 |
| 18. Program in Neuroscience and Cognitive Science, U. of Maryland, College Park, MD | 2007 |
| 19. Dept. of Mechanical Engineering, Johns Hopkins, Baltimore MD | 2007 |
| 20. Dept. of Philosophy, Univ. of Chicago, IL, USA | 2006 |

21. Dept. of Physiology, Northwestern U. Feinberg School of Medicine, Chicago, IL	2006
22. IGERT Seminar Series, Machines & Organisms, Cornell University, Ithaca, NY	2006
23. Neuroscience Program, Michigan State University, East Lansing, MI	2005
24. Dept. of Electrical and Computer Engineering, Univ. of Illinois Chicago, IL	2005
25. Neuroscience Program, Univ. of Illinois Urbana-Champaign, IL	2005
26. Dept. of Biology, McGill University, Montreal, QC	2005
27. Dept. of Physical Therapy & Human Movement Sci., Northwestern Univ.	2005
28. Dept. of Aeronautics and Astronautics, Univ. of Washington, Seattle, WA	2005
29. Committee on Computational Neuroscience, Univ. of Chicago, IL	2005
30. Evolutionary Discussion Group, Northwester Univ., Evanston, IL	2004
31. Sensory Motor Performance Program, Rehabilitation Institute of Chicago, IL	2003
32. IGERT Program on Dynamics of Complex systems, Evanston, IL	2003
33. Northwestern University Institute of Neuroscience, St. Charles, IL,	2003
34. Sloan Theoretical Neurobiology Seminar Series, Caltech, Pasadena CA	2002
35. Caltech Bioengineering Seminar Series, Caltech, Pasadena CA	2001
36. Beckman Institute Visualization Seminar Series, Urbana, IL	1998

CONTRIBUTED ACADEMIC TALKS AND SELECTED POSTERS

- 1) 2020 Neuromatch v3 (two talks)
- 2) 2019 Bernstein Conference on Computational Neuroscience (talk)
- 3) 2019 Cognitive Computational Neuroscience (poster)
- 4) 2019 Society for Neuroscience (2 posters)
- 5) 2018 J.B. Johnston Club for Evolutionary Neuroscience (talk)
- 6) 2018 Society for Neuroscience (talk)
- 7) 2018 International Congress of Neuroethology, Brisbane Australia (poster)
- 8) 2017 Adaptive Motion in Animals and Machines, Sapporo, Japan (poster)
- 9) 2016 J. B. Johnston Club for Evolutionary Neuroscience, San Diego, CA (talk)
- 10) 2016 Society for Vertebrate Paleontology, Salt Lake City, Utah (talk)
- 11) 2015 Adaptive Motion of Animals and Machines, MIT Cambridge MA (poster)
- 12) 2015 Society for Integrative and Comparative Biology, West Palm Beach FL (talk+poster),
- 13) 2013 Janelia Farms, Dynamics of Prey Capture and Escape (1 talk, 1 poster)
- 14) 2013 Society for Integrative and Comparative Biology, San Francisco (2 talks).
- 15) 2012 International Congress of Neuroethology, College Park, Maryland (2 posters).
- 16) 2012 International Conference on Intelligent Robots and Systems, Portugal (3 talks).
- 17) 2012 Fourth IEEE RAS/EMBS International Conference on Biomedical Robotics and Biomechatronics, Rome Italy (talk)
- 18) 2012 First International Workshop on Robotic Electrosense (3 posters, 3 talks)
- 19) 2011 American Physical Society, 64th Annual Meeting (poster)
- 20) 2009 American Physical Society, 62nd Annual Meeting (talk, presenter: Curet; talk, presenter Shirgaonkar; talk, presenter: Patankar), Minneapolis, MN

- 21) 2009 Society for Neuroscience (poster), Chicago, IL
- 22) 2009 Society for Integrative and Comparative Biology (talk), Boston, MA
- 23) 2008 American Physical Society, 61st Annual Meeting (talk, presenter: MacIver) San Antonio, TX
- 24) 2008 American Physical Society, 61st Annual Meeting (talk, presenter: Curet) San Antonio, TX
- 25) 2008 American Physical Society, 61st Annual Meeting (talk, presenter: Shirgaonkar) San Antonio, TX
- 26) 2008 American Physical Society, 61st Annual Meeting (video submission to Gallery of Fluid Motion, San Antonio, TX
- 27) 2007 American Physical Society, 60th Annual Meeting (talk, presenter: MacIver), Salt Lake City, UT
- 28) 2007 American Physical Society, 60th Annual Meeting (talk, presenter: Shirgaonkar), Salt Lake City, UT
- 29) 2007 American Physical Society, 60th Annual Meeting (talk, presenter: Curet), Salt Lake City, UT
- 30) 2007 American Physical Society, 60th Annual Meeting (poster, presenter: Curet), Salt Lake City, UT
- 31) 2007 International Congress of Neuroethology, Vancouver BC (talk)
- 32) 2007 International Congress of Neuroethology, Vancouver BC (poster)
- 33) 2007 International Congress of Neuroethology, Vancouver BC (poster)
- 34) 2007 International Congress of Neuroethology, Vancouver BC (poster)
- 35) 2007 IEEE International Conference on Robotics and Automation, Rome, Italy (talk)
- 36) 2006 Biomedical Engineering Society, Chicago, IL
- 37) 2006 Society for Neuroscience, Atlanta, GA (poster)
- 38) 2006 American Physical Society, 59th Annual Meeting, with Neelesh Patankar and Oscar Curet, Tampa, FL (talk, presenter: Shirgaonkar)
- 39) 2006 American Physical Society, 59th Annual Meeting, with Oscar Curet and Neelesh Patankar, Tampa, FL (talk, presenter: MacIver)
- 40) 2005 Developmental Basis of Evolutionary Change, Chicago, IL (poster)
- 41) 2005 Developmental Basis of Evolutionary Change, Chicago, IL (poster)
- 42) 2005 Joint Dept of Neurology and Biomedical Engineering Poster Session (with T. Kuiken & A. Schultz), Chicago, IL (poster)
- 43) 2005 Southern California Joint Symposium on Computational Neuroscience (with J. Burdick), California Institute of Technology, Pasadena CA (talk)
- 44) 2005 Neural Engineering Workshop (with J. Snyder), Chicago IL
- 45) 2004 International Soc. Neuroethology, Nyborg, Denmark (with J. Burdick & M. Nelson) (poster)
- 46) 2002 Gordon Research on Sensory Coding and the Natural Environment (with M. Nelson), South Hadley, MA (poster)
- 47) 2001 International Soc. Neuroethology, Bonn, Germany (poster with M. Nelson)
- 48) 2000 Society for Neuroscience 30th Meeting, New Orleans LA (poster with M. Nelson)
- 49) 1999 Computation and Neural Systems Meeting (CNS), Pittsburgh, PA (poster with M.

- Nelson)
- 50) 1998 International Soc. Neuroethology, San Diego, CA (poster with M. Nelson)
 - 51) 1997 Society for Neuroscience 27th Meeting, New Orleans, LA (poster with M. Nelson)
 - 52) 1996 Computation and Neural Systems Meeting (CNS), Boston, MA (poster with M. Nelson)
 - 53) 1995 Society for Neuroscience 25th Meeting, San Diego, CA (poster with M. Nelson)

ACTIVE FUNDING

How Ecology Induces Cognition: Paleontology, Machine Learning, and Neuroscience

Principal Investigator: Malcolm MacIver

Co-Investigator: Daniel Dombeck

Agency: National Science Foundation, ECCS 1835389

Period 9/1/2018-8/31/2022

COMPLETED FUNDING

Reticulospinal Execution of Innate Decision-Making

Principal Investigator: David McLean

Co-Investigators: Malcolm MacIver, Neelesh Patankar

Agency: National Science Foundation, IOS-ORG 1456830

Period: 5/01/2015-4/30/2019

NRI: Electrosense imaging for underwater telepresence and manipulation

Principal Investigator: Michael Peshkin

Co-Investigators: Malcolm MacIver, Joshua Smith, Konrad Kording, Alex Mahklin.

Agency: National Science Foundation, NSF IIS-1427419

Period: 9/1/2014-8/31/2019

Development of a climate change prediction market for behavioral change

Principal Investigator: Malcolm MacIver

Co-Investigator: Moran Cerf

Agency: Northwestern Institute on Complex Systems

Period 03/01/2015-11/01/2018

A Bio-Inspired underwater robot for station keeping with omnidirectional disturbances

Principal Investigator: Malcolm MacIver

Co-Investigators: Michael Peshkin, Todd Murphey.

Agency: Office of Naval Research, N00014-14-1-0594.
Period: 5/1/14-9/30/17

Cyber-Enabled Discovery in Neuromechanical Systems

Principal Investigator: Malcolm A. MacIver

Co-Investigators: Noah Cowan and Eric Fortune (Johns Hopkins), George Lauder (Harvard)

Agency: National Science Foundation, NSF CMMI-0941674

Period: 9/1/2009-8/31/2015

CAREER: Infomechanics - The interdependence of animal information acquisition and mechanics

Principal Investigator: Malcolm MacIver

Agency: National Science Foundation, IOB-0846032

Period: 8/15/2009-6/30/2015

IGERT: Integrative Training in Motor Control and Movement

Principal Investigator: Melina Hale (University of Chicago)

Co-Investigator: Malcolm A. MacIver, and three others at University of Chicago

Agency: National Science Foundation

Period: 8/1/2009-7/31/2014

The development of a bio-inspired magneto-electrosensory navigation system

Principal Investigator: Malcolm MacIver

Co-Investigators: Kinea Design LLC, Michael Peshkin, Kevin Lynch

Agency: Office of Naval Research, STTR mechanism, Phase II, N00014-10-C0420

Period: 1/5/2010-12/1/2012

Fully resolved simulation of self-propelling fish

Principal Investigator: Neelesh A. Patankar

Co-Investigator: Malcolm A. MacIver

Agency: National Science Foundation, CBET-0828749

Period: 9/1/2008-8/31/2012

scale

Principal Investigator: Malcolm MacIver

Co-Investigators: Jay Allan Yim, School of Music at Northwestern University, and Marlina Novak, Weinberg College of Arts and Sciences at Northwestern University.

Agency: Northwestern Center for Interdisciplinary Research in the Arts

Period: 7/15/2009-7/14/2010

The development of a bio-inspired magneto-electrosensory navigation system

Principal Investigator: Malcolm MacIver

Co-Investigators: Kinea Design LLC, Michael Peshkin, Kevin Lynch

Agency: Office of Naval Research, STTR mechanism
Period: 6/29/2009-1/25/2010

Transforming sensory signals into muscle activations in a behavior with dynamic constraints

Principal Investigator: Malcolm A. MacIver
Co-Investigator: Kevin Lynch (ME)
Agency: National Science Foundation IOB-0517683
Period: 8/1/2005-10/2008

PUBLIC ENGAGEMENT (LINKS ACTIVE IN ELECTRONIC PDF)

Public Lectures/Interviews

2018 New Zealand Science Festival, Dunedin New Zealand. [Robots: The New Generation](#).

2016 reddit “Ask Me Anything” [PLOS Science Wednesday](#), on our PLOS paper on the convergent evolution of mechanically optimal swimming.

2015 Northwestern University, Lawrence B. Dumas Domain Dinner on New Technologies That Will Be Transformative. Talk title: *Engineering Empathy*

2015 Chicago Museum of Science and Industry, public talk on Electric Fish Robotics in association with their new exhibition on robotics, *Robot Revolution*.

2014 Chicago Council on Science and Technology talk and panel discussion on *The Future of Work*. [Video at this location](#) (<https://www.youtube.com/watch?v=PcQ68vTPXb4>)

2014 PBS TV affiliate WTTW panel discussion on the *Future of Work*, Chicago Tonight. [Video at this location](#) (<http://chicagotonight.wttw.com/node/17033>)

2014 *Big Data in Neuroscience*, talk for the Shirley Ryan Learning for Life Series.

2014 *Cheetahs, Fish, Fingers & Bacteria: The coming menagerie of mechanical cohabitants*. Panel discussion for the Adler Planetarium public event “Hops’n Bots”, with Sangbae Kim (MIT), Antonio Bicci (University of Pisa), and Bradley Nelson (ETH Switzerland).

2014 *The Future of Artificial Intelligence*, interview with the creators of the CBS TV Series *Person of Interest* for Season 3 DVD Extra. [Video at this location](#), at two minutes forty seconds (https://www.dropbox.com/s/2hlp6805vgbwee0/PERSON_OF_INTEREST_S3_DISC_6.m4v?dl=0)

2014 BBC World Service (Interview) on developing robotic fish.

2014 BBC Radio 5 (Interview) on the development of a robot fish.

2014 BBC *Amazon electric fish inspire underwater robotics*. [Story and video at this location](#) (<http://www.bbc.com/news/science-environment-26025563>).

2013 Interview by Jennifer Ouellette for the show Virtually Speaking Science on my biography, science advising to movie makers, and a variety of science topics. [Audio at this location](#) (<http://www.blogtalkradio.com/virtually-speaking-science/2013/09/12/jennifer-ouellette-malcolm-maciver-neuroprosthetics-1>)

2013 *Can We Expand Our Consciousness With Neuroprosthetics?* TEDx Caltech, January 2013. Pasadena CA. [Video at this location](#) (<https://www.youtube.com/watch?v=gj2zx1kEjKM&list=PLsRNoUx8w3rP8morYo0ZmBAwrEpJVr51X>)

2013 Discovery Science Channel, *Alien Encounters* Season 2, Episodes 1-2, Commentator, March 2013.

2012 *From electric fish to robot fish and back* PINC Conference, Amsterdam

2010-2012. Blogger on robotics, artificial intelligence, and neuroscience for Science Not Fiction, Discover Magazine. Links to posts above.

2011 “Death and the Powers” Public panel on the new robot opera by Tod Machover, with Tod Machover, March 2, 2011, Dean’s Seminar Series, McCormick School of Engineering, Northwestern University. Article and video: http://www.mccormick.northwestern.edu/news/articles/archive/2009-2012/article_852.html

2011 *Science of Cyborgs* March 1, 2011, Directors Guild of America, Los Angeles CA. Talk on movie portrayals of robotics and androids, transhumanism, and the evolutionary basis of consciousness. Article and video of presentation: <http://www.scienceandentertainmentexchange.org/blog/science-cyborgs>

2011 Interview on NPR Chicago affiliate WBEZ *Clever Apes* radio program on the origin and history of consciousness. [Story and audio here](#) (<http://www.wbez.org/blog/clever-apes/2011-05-24/clever-apes-13-origin-stories-86999>)

2010 Interview on the National Academy of Engineering Innovation Podcast and Radio Series *Body Intelligence--Does all cleverness and intelligence come from our brains? That may seem logical, but may not be the case*. [Audio here](#) (<http://www.nae.edu/Projects/20730/wtop/27253.aspx>)

- 2010 Science Café “The Evolution of Consciousness” March 17, 2010, Firehouse Grill Evanston IL. [Media coverage of event](https://helix.northwestern.edu/article/thinking-about-next-move-350-million-years-consciousness) (https://helix.northwestern.edu/article/thinking-about-next-move-350-million-years-consciousness).
- 2010 Interview on NPR Chicago affiliate WBEZ *Clever Apes* radio program on the electric fish art installation “scale”. [Story and audio here](http://www.wbez.org/blog/clever-apes/clever-apes-light-sabers-and-fish-choir) (http://www.wbez.org/blog/clever-apes/clever-apes-light-sabers-and-fish-choir)
- 2009-2010 Blogger for the Science in Society Blog, Feinberg School of Medicine. <http://blog.scienceinsociety.northwestern.edu/author/mmaciver/>
- 2009 Science consultant for TRON Legacy, as part of the National Academy of Science’s “Science Entertainment Exchange Program” to bring better science to Hollywood.
- 2009 Lecturer for the Illinois Science Council’s Science Café “Body Electric: Lightning, defibs, and Tasers” at Lucky Strike (AMC Theater Building), 322 E Illinois St., Chicago IL.
- 2003 NSF High School Teacher Program, worked with a Los Angeles inner city school district teacher to bring biofluids research to high schools
- 2003 NSF & Caltech sponsored art show, Williamson Gallery in Pasadena, interactive art installation on active sensing with Simon Penny. More details at <http://www.neuromech.northwestern.edu/uropatagium/#ArtSci>

Select Blog Posts

B37. Information Wants to Be Free. What About Killer Information? [Discover Magazine Online. Dec 27, 2011.](#)

B36. The Geek Rapture and Other Musings of William Gibson [Discover Magazine Online. Oct 17, 2011.](#)

B35. Why Did Consciousness Evolve, and How Can We Modify It, Pt. III: Memory, Communication, and Perception [Discover Magazine Online. Aug 8, 2011.](#)

B34. Why Did Consciousness Evolve, and How Can We Modify It, Pt. II: The Supremacy of Vision [Discover Magazine Online. Mar 23, 2011.](#)

B33. Why Did Consciousness Evolve, and How Can We Modify It? [Discover Magazine Online. Mar 14, 2011.](#)

B32. Transhumanism: A Secular Sandbox for Exploring the Afterlife? [Discover Magazine Online. Feb 28, 2011.](#)

B30. A Robots That Evolve Like Animals Are Tough and Smart—Like Animals [Discover](#)

[Magazine Online. Feb 14, 2011.](#)

B29. A Does AI Need Guts to Get to the Singularity? [Discover Magazine Online. Feb 2, 2011.](#)

B28. A New Robot for the Bestiary: How to Build a Robotic Ghost Fish [Discover Magazine Online. Jan 26, 2011.](#)

B27. The Real-Life District 9—Class and Sci-Fi in South Africa [Discover Magazine Online. Jan 12, 2011.](#)

B26. Would Death Be Easier If You Know You've Been Cloned? [Discover Magazine Online. Dec 27, 2010.](#)

B25. Killing The Dr. Evils of Iran: Is it Open Season On Scientists? [Discover Magazine Online. Nov 30, 2010.](#)

B24. How to Conduct the World's First Electric Fish Orchestra [Discover Magazine Online. Nov 23, 2010.](#)

B23. Mutants, Androids, Cyborgs and Pop Culture Films [Discover Magazine Online. Nov 2, 2010.](#)

B22. Electric Fish "Plug in" and Turn Their Zapping Into Music [Discover Magazine Online. Oct 23, 2010.](#)

B21. Caprica Puzzle: If a Digital You Lives Forever, Are You Immortal? [Discover Magazine Online. Oct 5, 2010.](#)

B20. I Have Seen the Furniture, and It Is Robotic, [Discover Magazine Online. Sept 28, 2010.](#)

B19. A Robot Science Fiction and the Modding of Our Future, [Discover Magazine Online. Sept 22, 2010.](#)

B18. A Robot That Tries To Rock You Asleep, [Discover Magazine Online. Sept 14, 2010.](#)

B17. Is AI More Common Than Biological Intelligence Across the Universe?, [Discover Magazine Online. Aug 31, 2010.](#)

B16. The New AI: Turn Robots Into Infant Scientists, [Discover Magazine Online. Aug 25, 2010.](#)

B15. Amplifying Our Brain Power Through Better Interactive Holographics, [Discover Magazine Online. Aug 10, 2010.](#)

B14. Inception and the Neuroscience of Sleep, [Discover Magazine Online. Aug 10, 2010.](#)

B13. Why Keep Your Body? Help Yourself to Big Muscles, Cyborg Limbs, and a Big Booty, [Discover Magazine Online. Jul 27, 2010.](#)

B12. When Sci-Fi Plays Play With Your Identity, [Discover Magazine Online. Jul 19, 2010.](#)

B11. Hairshirted Eye for the Irritable Guy: New Study Shows How the Feel of Things Affects Thought, [Discover Magazine Online. Jul 7, 2010.](#)

B10. IBM Computer Fails the Turing Test But Just Might Pass the Jeopardy Test. Science Not Fiction Blog, [Discover Magazine Online. June 28, 2010.](#)

B09. The Animal Superpower That Robots Would Love to Have: Great Efficiency. Science Not Fiction Blog, [Discover Magazine Online. June 18, 2010.](#)

B08. Guest Post: Malcolm MacIver on War with the Cylons. [Sean Carroll's Blog, April 26 2010.](#)

B07. Are we 'wired for war' with cylons? [Science and Society Helix Blog, Feb 11, 2009.](#)

B06. "A scary thing happened" --- How to make child's play of disasters. [Science and Society Helix Blog, June 5, 2009.](#)

B05. Homeopathy and the limits of science. [Science and Society Helix Blog, April 5, 2009.](#)

B04. Is it time to shut down the national center for complementary and alternative medicine (NCCAM)? [Science and Society Helix Blog, March 23, 2009.](#)

B03. The Science Entertainment Exchange, Pt II. [Science and Society Helix Blog, Feb 25, 2009.](#)

B02. The Science Entertainment Exchange, Pt II. [Science and Society Helix Blog, Feb 25, 2009.](#)

B01. The Science Entertainment Exchange, Pt II. [Science and Society Helix Blog, Feb 25, 2009.](#)

TRAINEE FELLOWSHIPS

2013-2016 Kiran D. Bhattacharyya, NSF Graduate Fellowship

2013-2015 Matt Green, NSF Postdoctoral Fellowship

2006-2010 Oscar Curet, Diversifying Higher Education Faculty in Illinois Graduate Fellowship

MENTORING

Postdoctoral Associates

Matthew Hobson Green, 2012--

Srinivas Ramakrishnan (Co-supervised with N. Patankar), 2009. Current position: Senior Software Developer at ANSYS, Inc.

Anup Shirgaonkar (Co-supervised with N. Patankar), Current position: Quantitative Strategist in Investment Management, Quantitative Machines.

Claire Postlethwaite (Co-supervised with M. Silber), 2006-Jun 2008: Assistant Professor, University of Auckland, New Zealand.

Graduate Students

Current Ph.D. students

German Espinosa, Computer Science

Alexander Lai, Biomedical Engineering

Current M.S. in Robotics students

Senthil Palanisamy

Completed Ph.D. students

Ugurcan Mugan, Biomedical Engineering. Current position: Postdoctoral scholar, David Redish laboratory.

Kiran D. Bhattacharyya, Biomedical Engineering. Current position: Robotics engineer, Intuitive Surgical.

Chen Chen, Biomedical Engineering. Current position: Sensor technologies, Apple Computer.

Yang Bai, Mechanical Engineering (with Michael Peshkin). Current position: Machine learning researcher at Google.

Izaak Neveln, Biomedical Engineering. Current position: Postdoctoral scholar in Simon Sponberg's laboratory, Georgia Tech, School of Physics & School of Applied Physiology.

Brad Patterson, Northwestern University Interdepartmental Neuroscience Program. (with David McLean). Current position: In training to be a US Army intelligence officer.

James Snyder, Biomedical Engineering. Current position: Engineering consultant and technology developer for embedded systems.

Rahul Bale, Mechanical Engineering (with Neelesh Patankar). Current position: Postdoc, RIKEN, Japan.

Oscar Curet (with N. Patankar), Mechanical Engineering (2003-2009). Current position: Assistant Professor, Department of Ocean and Mechanical Engineering, Florida Atlantic University, Boca Raton.

Michael Epstein, Mechanical Engineering (with E. Colgate) (2003-2007). Current position: Consulting.

James Solberg, Mechanical Engineering (with K. Lynch) (2003-2007). Current position: Senior Controls Engineer, HDT Expeditionary Systems Inc., Evanston IL.

Completed Masters students

Jordan Haskel

Levi Todes (Robotics, 2019)

Michael Wiznitzer (Robotics, 2018)

Luke Shi (Robotics, 2018)

Abhishek N. Patil (Robotics, 2016)

Sandra Fang, Mechanical Engineering (2014-2016), Current position: JPL.

Ritwik Ummalneni (Robotics, 2016)

Sun Yue (Robotics, 2015)

Yoni Silverman, Mechanical Engineering (2010-2013). Current position: Research engineer at a Chicago area nuclear power controls company.

Aimee Schultz, Mechanical Engineering (2004-2007). Current position: Self-employed academic science paper writer.

Thesis Committees

Brad Radvansky, Dept. of Neurobiology, PhD

Tommy Berrueta, ME, PhD

Georgios Mamkoukas, ME, PhD

Ana Pervan, ME, PhD

Meagan Bechel, BME, PhD

Peter Winter, Chemical and Biological Engineering, PhD

Thomas Harmon, Northwestern Interdepartmental Neuroscience Program, PhD

David Meyer, Mechanical Engineering, PhD

James Aaron Ellis, Biomedical Engineering, MS

Mao Mao, Mechanical Engineering, PhD

Elliot Johnson, Mechanical Engineering, PhD

Matthew Geary, Biomedical Engineering PhD

Brian London, Northwestern Interdepartmental Neuroscience Program PhD

Dhwanil Damania, Biomedical Engineering MS

Vladimir Turzhitsky, Biomedical Engineering PhD

Hariharan Subramanian, Biomedical Engineering PhD

Lexyne McNealy, Department of Physical Medicine and Rehabilitation MS

Michael Siegel, Biomedical Engineering MS

Albert Chen, Biomedical Engineering, PhD

Northwestern University Interdepartmental Neuroscience Program Student 3 Month Rotations:

Sam Minkowicz (2017), Chris Mullens (2010), Ricardo Ruiz-Torres (2009), Lydia Wood (2005), Brian London (2004)

Undergraduate Students

2016 Alfred Astor, Mechanical Engineering & Neurobiology

2015 Jonathan Denose (Electrical Engineering, URM), Michael Smith (Computer Science, URM), Nicholas Ohl (Biomedical Engineering).

2013-2015 Scott Schaper, Mechanical Engineering

2014 Adam Birnbaum

2012-2014 Alexandra Faye Salomon, HHMI Mentoring Fellows Program

2011-2013 Aliza Abraham, Integrated Science Program

2010-2011 Ethan Coffel, Computer Engineering and Integrated Science Program

2010 Leland Gossett, Biomedical Engineering (**Scale** project)

2010 Chris Semple, Biomedical Engineering (**Scale** project)

2010-2011 Kyle Liske, Mechanical Engineering (**Scale** project)

2009-2010 Uzair Admani, Biomedical Engineering

2009-2010 Omar Hassan, Biomedical Engineering

2009 Aravinda Gunda, SINE Intern, George Washington University

2008-2009 Jad Carson, Biomedical Engineering

2008-2009 Benjamin Proznitz, Dept. of Eng Sci and Applied Math

2007-2008, Jangir Selimkhanov, Dept. of Eng Sci and Applied Math

2007-2008, Alec Zopf, Dept. of Biomedical Engineering

2006-2007 Irene Chiang, Dept. Biochemistry, Molecular, and Cell Biology

2006-2007 Alfred Shoukry, Biomedical Engineering

2006-2007 Vicky Huang, Biomedical Engineering

2005-2006 Clif Lin, College of Arts and Science, Northwestern (with T. Kuiken)

2004-2007 Tiffany Keung, Biomedical Engineering, Northwestern 2003-2004

2004-2005 Marie Kyle, Mechanical Engineering, Northwestern (with E. Colgate)

2004-2005 Elana Green, Mechanical Engineering, Northwestern (with E. Colgate)

2004-2006 Colin Tan, Biomedical Engineering, Northwestern

2004-2005 Karin Stensvad, Mech Engineering, Washington University (with E. Colgate)

2004-2005 Beth Lapour, Mechanical Engineering, Northwestern (with E. Colgate)

2004-2005 Ani Chatterjee, Biomedical Engineering, Northwestern

TEACHING**Teaching-Northwestern University. Courses Developed:**

Scientific and embedded programming with python (ME224).

Emergent Horizons (DSGN 495/ART 390, with Iñigo Manglano-Ovalle from Dept of Art Theory and Practice, Cross listed between School of Engineering and Dept of Art Theory and Practice)

Risk (DSGN 495/ART 390, with Michael Rakowitz from Dept of Art Theory and Practice, Cross listed between School of Engineering and Dept of Art Theory and Practice) 2016

Water (DSGN 495/ART 390, with Michael Rakowitz from Dept of Art Theory and Practice, Cross listed between School of Engineering and Dept of Art Theory and Practice) 2015

Artists & Engineers Collaborate (DSGN 495, with Jeanne Dunning from Dept of Art Theory and Practice, Cross listed between School of Engineering and Dept of Art Theory and Practice) 2014

Computational neuromechanics and neuroethology (BME 461) 2004-present

Neuromechatronics (BME 464) 2004-2013

Teaching-Northwestern University

Advanced systems physiology: Neuroscience (BME401) 2018-present

Scientific and embedded programming with python (ME224) 2018-present

Analysis of Biological Systems (BME 306) 2015-present

Design Thinking and Communication (DTC) 2013-present

Professional Essentials (ME 513) 2008-present

“Experimental Engineering” (ME 224) 2007-2017

Introduction to Biomechanics (BME 271) 2009-2013

IDEA 298 Faculty Advisor for Submersible Team 2007

“Honors Eng. Analysis 3” 2004-2006

Other Teaching

University of Otago, Dunedin NZ, The evolution of planning, Zool 314, Zool 412, Jul 11 & Jul 13 2018.

Zygon Center for Religion and Science, Chicago IL, Situated Brain and Mind Seminar: “Situated Nervous Systems and Cognition” Feb 18, 2013.

Northwestern University, National High School Institute Cherubs, Theatre Arts Program, guest instructor for “Theatre for Nerds” elective, July 7-8, 2009.

Gulbenkian Research Institute, Portugal, “Normative Theories of Brain Function” Feb 2008

University of Chicago, guest lecturer, Dept. of Philosophy/HIPS, William Wimsatt and John Haugeland, “Boundaries, Modules and Levels” Feb 2006

Guest lecturer, “Animal Behavior” Northwestern University 2004

Teaching Prior to Northwestern University

University of Illinois, “Neurophysiology Laboratory” (PHYSL 416) 1/97-5/97

University of Illinois, “Topics in Neuroethology” (PHYSL 490) 8/96-12/96

University of Illinois, “Introduction to Neurobiology” (BIO 303) 8/94-12/94

Indiana University, “Introduction to Philosophy” (P100) 1/94-5/94

University of Toronto, “How Computers are Used” (CSC104) 1/91-5/91

Indiana University, “Introduction to Ethics” (P140) 9/92-12/92

University of Toronto, “How Computers are Used” (CSC104) 9/91-12/91

University of Toronto, “Computer Programming” (CSC108)	9/90-12/90
University of Toronto, “Science and Pseudo Science” (PHL272)	1/89-7/89
Confederation College, Thunder Bay ON. Digital Electronics, Programming	1/86-4/86

SERVICE

Memberships

International Society of Neuroethology
The J.B. Johnston Club for Evolutionary Neuroscience
Society for Neuroscience
Institute of Electrical and Electronics Engineers
American Physical Society

Scientific Review Panels

NSF Ad-Hoc for Animal Sensation and Movement, and Neural Cluster Program Panels, 2007-present; NSF Neural Cluster Program Panel Meeting, 2008; NSF Animal Sensation and Movement Program Panel Meeting, 2006; MIT Sea Grant College Program, 2006; NIH Sensorimotor Integration Study Section, 2004.

Conference Organization

Organizer: 10th International Symposium on Adaptive Motion of Animals and Machines, 2018 Chicago IL.
First International Workshop on Robotic Electrolocation, August 3 2012, College Park Maryland.
International Society for Neuroethology Symposium “Coupled Robot-Animal Systems,” Spain 2010

Reviewer for the Following *Journals* and Conferences

Advanced Robotics
Animal Biology
Autonomous Robots
Bioinspiration and Biomimetics
Biological Cybernetics
Behavioral and Brain Sciences
Brain, Behavior, and Evolution
Complexity
Cognitive Computational Neuroscience Conference
Current Biology
eLife
Frontiers in Behavioral Neuroscience
IEEE Conference on Robotics and Automation

IEEE Journal of Oceanic Engineering
IEEE Proceedings
IEEE Transactions on Robotics
IEEE Sensors Journal
Integrative and Comparative Biology
International Journal of Robotics Research
International Conference on Artificial Neural Networks
International Congress of Neuroethology
Journal of Biomechanics
Journal of Comparative Physiology
Journal of Experimental Biology
Journal of Neuroscience
Journal of the Royal Society Interface
Journal of Visualized Experiments
Nature Communications
Neurocomputing
Physical Biology
PLoS Computational Biology
PLoS Biology
Proceedings of the National Academy of Sciences
Proceedings of the Royal Society B
Robotics Science and Systems
Science
Science Robotics

Current/Past Advisory Boards

2015—subCULTron Advisory Board, European Union (H2020 Project no. 640967), a group of 14 scientists from Italy, Austria, Belgium, Croatia, Germany, and France building a swarm of autonomous underwater robots.

2007-2013 FILOSE Advisory Board Member (of three). FILOSE (Robotic FIsh LOcomotion and Sensing) is a FP7-ICT-2007-3 STREP research project financed by the European Union 7th Framework Program, headed by the Tallinn University of Technology in Estonia, with partners Riga Technical University of Latvia, the Italian Institute of Technology in Genova, and the Universities of Verona and Bath UK. Web site: http://www.biorobotics.ttu.ee/tikiwiki_filose/tiki-index.php.

University Service

2019-present Research Integrity Committee, Northwestern University
2019-present Office for Research Limited Submissions Advisory Committee
2018-present Promotion and Tenure Committee, McCormick School of Engineering
2016-present Dept. of Biomedical Engineering, Director of Graduate admissions
2015-present Northwestern Institute on Complex Systems, neuroscience subgroup lead
2015-present BME Undergraduate Program Committee, Faculty Community Committee

- 2013-present Segal Design Institute, Research Council Executive Committee Member
- 2009-present Tech and Ford Safety Committee, Safety Officer for Department of Biomedical Engineering and Department of Mechanical Engineering
- 2015 Interviewee for Program Review of the Department of Neurobiology
- 2014-2015 Northwestern Neuroscience Proposed Major Steering Committee
- 2011-2013 Faculty Senate representative, Department of Biomedical Engineering
Faculty Senate Committee Chair, Secure Faculty Survey
- 2009-2013 Committee on Animal Resources
- 2011 Northwestern Interdepartmental Neuroscience Program Review Committee
- 2009-2010 Freshman Advising
- 2008-2009 BME Admissions Committee
NUIN Student Interviews
Organized and ran the ME Dept. Professional Skills graduate seminar series
Freshman Advising
- 2007-2008 ME Control and Manufacturing Search Committee
Organized and ran the ME Dept. Professional Skills graduate seminar series
Interdisciplinary Committee on Evolutionary Processes
NUIN Student Interviews
- 2006-2007 ME Target of Opportunity Ad-hoc Hiring Committee
Department of Neurobiology and Physiology Hiring Committee
ME Undergraduate Laboratory Course Renewal Committee
NUIN Admissions Committee
Interdisciplinary Committee on Evolutionary Processes
- 2005-2006 Dept. of Neurobiology and Physiology & Department of Physics and Astronomy
Hiring Interdepartmental Hiring Committee
Dynamics and Complex Systems IGERT, managed seminar series on the
Mechanics of Locomotion
- 2004-2005 BME Departmental Website Faculty Liaison
BME Graduate Student Admissions Committee
BME Web Site Faculty Liaison
BME/Department of Physical Medicine and Rehabilitation Neural Engineering
Hiring Committee
BME/RIC Neural Engineering Hiring Committee
ME/BME Neural Engineering Hiring Committee
NUIN Retreat Planning Committee
Research Data Integration and Assessment System Development Committee
- 2002-2003 Summer Minority Undergraduate Research Program mentor, Caltech

SELECT MEDIA COVERAGE

2019 Sean Carroll's Mindscape Podcast, Episode 39: [Malcolm MacIver on Sensing, Consciousness, and Imagination](#).

2018 Radio New Zealand, Our Changing World. Robots - Nao and the Bristlebots. Interview with Mike Paulin by Allison Ballance on our New Zealand Science Festival engagement in Dunedin New Zealand on July 12, 2018. <https://www.radionz.co.nz/national/programmes/ourchangingworld/audio/2018653987/robots-nao-and-the-bristlebots>

2018 New Zealand Herald. Robot butlers: Don't expect them any time soon. Interview with Jamie Morton. https://www.nzherald.co.nz/nz/news/article.cfm?c_id=1&objectid=12086561

2018 When Stunning Won't Kill, Fish Use Electricity to Communicate. <https://www.insidescience.org/news/when-stunning-wont-kill-fish-use-electricity-communicate>

2017 SciTechNow, PBS TV. Interview by Hari Sreenivasan on PNAS study about why fish came on to land 385 million years ago, initial broadcast July 24 2017. <http://www.scitechnow.org/videos/data-reveals-long-ago-fish-made-leap-onto-land/>

2017 Fish Changed in a Surprising Way Before Invading Land. Ed Yong, The Atlantic Online, March 8 2017. <https://www.theatlantic.com/science/archive/2017/03/in-the-invasion-of-land-big-eyes-came-before-strong-legs/518883/>

2017 Why Did Life Move to Land? For the View. Jennifer Ouellette, Quanta Magazine, March 7, 2017. <https://www.quantamagazine.org/why-did-life-move-to-land-for-the-view-20170307/>

2015 ASME Mechanical Engineering Magazine. Ghost Knifefish in the Machine. https://www.dropbox.com/s/qq7ndhkl3hbfsyd/Ferb15a_electrosense_ASME.pdf?dl=0

2015 New York Times Science Take (Video + Article) The Right Ratio to Engineer a Swim. <http://www.nytimes.com/2015/05/11/science/the-right-ratio-to-engineer-a-swim.html>.

2015 Washington Post. How 22 diverse ocean creatures ended up using the same swim stroke. <http://www.washingtonpost.com/news/speaking-of-science/wp/2015/04/28/how-22-diverse-ocean-creatures-ended-up-using-the-same-swim-stroke/>

2015 Los Angeles Times. Would animals swim differently on an alien planet? <http://www.latimes.com/science/sciencenow/la-sci-sn-swimming-animals-convergent-evolution-ocean-bioinspired-alien-20150428-story.html>

2015 PLOS Biology Perspective Convergence on an Optimal Way to Swim, DOI: 10.1371/journal.pbio.1002124. <http://journals.plos.org/plosbiology/article?id=10.1371/journal.pbio.1002124>

2015 Journal of Experimental Biology Perspective, Life converges on solutions to swim optimally. <http://jeb.biologists.org/content/218/17/2663.2.full>

2015 CBS. Movements of fish, bats inspire next-gen robots. <http://www.cbsnews.com/news/movements-of-fish-bats-could-inspire-better-robots/>

2014 Entertaining Science—Scientific advisers for films and television help to bring credibility to the screen — and take some tangible and intangible benefits back to the lab. *Nature*, 3 July 2014, vol 511, p. 113-114. <http://www.nature.com/naturejobs/science/articles/10.1038/nj7507-113a>

2014 How Does a Chicken Tell Time? The New Yorker <http://www.newyorker.com/tech/elements/how-does-a-chicken-tell-time>

2014 Electric Eels Use Their Zaps to Remotely Control Prey. *Popular Mechanics*. <http://www.popularmechanics.com/science/animals/a13205/this-is-what-an-electric-eel-shocks-does-17493859/>

2014 Entertaining Science—Scientific advisers for films and television help to bring credibility to the screen — and take some tangible and intangible benefits back to the lab. *Nature*, 3 July 2014, vol 511, p. 113-114.. <http://dx.doi.org/10.1038/nj7507-113a>

2014 BBC TV: Robot builders inspired by animal kingdom. <http://www.bbc.com/news/science-environment-26222542>

2013 PBS Chicago affiliate WTTW Scientific Chicago with Neil Shubin on development of our electric fish robot. <http://chicagotonight.wttw.com/2013/11/26/scientific-chicago-neil-shubin>

2012 Popular Mechanics, “Meet the Scientists who Make Science Believable” Jan 17, 2012. <http://www.popularmechanics.com/culture/movies/a11747/scientific-advisors-to-the-stars/>

2011 New York Times, “A Beijing Exhibition on Art for the 'Post-Human Era', August 11, 2011. <http://www.nytimes.com/2011/08/12/arts/12iht-translife12.html>.

2011 Profile by the National Academy of Science’s **Science Entertainment Exchange**, June 2, 2011. <http://bit.ly/j3lcPX>.

2011 Written By, April/May 2011. The science and fiction toybox, by Louise Farr. Magazine article on work with science fiction movie and TV makers by the trade magazine of the writer’s guild of America.

2011 Video press release on new fish robot and results published in *J. Royal Society Interface* (2010), <http://bit.ly/ZKM8h>.

2010 Fast Company. Robotic ghost knifefish swims in every direction, causes brainiacs to high-five. <http://www.fastcompany.com/1718785/robotic-ghost-knifefish-swims-every-direction-causes-brainiacs-high-five-video>

2010 MSNBC. Electric fish could be model for underwater robots. [http://www.nbcnews.com/id/40787244/ns/technology_and_science-innovation/t/electric-fish-could-be-model-underwater-robots/ - .Vgb9prR6ejk](http://www.nbcnews.com/id/40787244/ns/technology_and_science-innovation/t/electric-fish-could-be-model-underwater-robots/- .Vgb9prR6ejk)

2010 Wired Magazine. Black Ghost Knifefish Robot Unmasks Movement Secrets. <http://www.wired.com/2010/12/robot-fish-ribbon-fin/>

2010 National Association of Engineering, Engineering Innovation Podcast and Radio Series. Body Intelligence. Broadcast on WTOP in Washington DC on March 21, 2010. [Does all cleverness and intelligence come from our brains? That may seem logical, but may not be the case.](#)

2010 Interview on Tron and Caprica involvement: Engineering Professor and Caprica Science Consultant Malcolm MacIver. ScriptPhD <http://is.gd/aP2Hk>.

2010 C is for Caprica. Story on involvement with Caprica show. National Academy of Science Science Entertainment Exchange. <http://is.gd/a8j8l>.

2010 Beckman Institute for Advanced Science and Technology, University of Illinois at Urbana Champaign Alumni Profile <http://is.gd/a8iCT>.

2010 Northwestern University News: Robotics Expert Lends a Hand in 'Caprica' <http://is.gd/a8jTI>.

2009 ProPublica: “Stimulus for Cotton Candy, Tango and a Fish Orchestra? Wacky, or Actually Worthy?” <http://is.gd/4O7Vs>

2009 A Shark’s Sixth Sense (interview on electroreception in sharks for Shark Week). Chicago Tribune, August 6 2009, <http://tinyurl.com/nfsq9u>, and Feinberg Science and Society featured article <http://tinyurl.com/lahfv5>.

2007 Robotic submersibles take on fish-like sensing abilities. **engadget** technology blog <http://tinyurl.com/37pvm4>.

2007 Electric fields could give subs ‘fish-like’ sense. New Scientist Tech 2007 <http://tinyurl.com/m27oxo>.

2003 Avant science; Artists and scientists both think creatively, so why not match them in projects showcasing new research? In Pasadena, the results have been adventurous. By Suzanne Muchnic *The Los Angeles Times*. Los Angeles, CA, USA, Feb 16 2003. page E.41, <http://tinyurl.com/13uwbe>.

2003 What Is It Like To Be a Fish? By Margaret Wertheim, *LA Weekly*, Los Angeles, CA, USA. April 11, 2003, <http://tinyurl.com/ku8azp>.

2003 Neuro Art Show: *LA Weekly* Pick of the Week, May 9, 2003, <http://tinyurl.com/mkgaoj>.

2003 'Neuro': Engineering Art and Science. By Lance Carlson, *Art Week*, July/August 2003, p. 24-25, <http://tinyurl.com/l9ee8d>.